

# Aneri Muni

Contact: [aneri.muni@gmail.com](mailto:aneri.muni@gmail.com)

Website: [amuni3.github.io](http://amuni3.github.io)

EDUCATION	<b>University of Montreal (UdeM) / Mila</b> Ph.D. Computer Science <i>Advisor:</i> Dr. Pierre-Luc Bacon	May, 2022 - Present
	<b>ETH Zurich (Eidgenössische Technische Hochschule)</b> MSc. Robotics, Systems and Control <i>Advisor:</i> Prof. Dr. Andreas Krause <i>Thesis:</i> Safe Learning-based Control in High-dimensional Spaces	2018 - 2021
	<b>Georgia Institute of Technology</b> BSc. Electrical Engineering, Minor in Robotics, Co-op Rotation Graduated with Highest Honors <i>Thesis:</i> 3D Reconstruction of Live Chickens in Poultry Houses	2013 - 2018
ACADEMIC RESEARCH	<b>Mila Research Institute</b>   <i>Advisor:</i> Dr. Pierre-Luc Bacon Visiting Student Researcher	Feb. 2021 - August 2021
	<ul style="list-style-type: none"><li>Proposed algorithms to design synthetic antimicrobial peptides in high-dimensional molecular spaces using Meta Reinforcement Learning and Bayesian Optimization.</li></ul>	
	<b>ETH Zurich</b>   <i>Advisor:</i> Prof. Dr. Andreas Krause <i>Safe Learning-Based Control in High-dimensional Spaces</i>	April 2020 - Jan. 2021
	<ul style="list-style-type: none"><li>Implemented safe Bayesian optimization algorithm with Sim2Real approach for position control of quadrotors.</li><li>Employed genetic algorithms to identify controllers that efficiently trade-off safety and performance.</li></ul>	
	<b>ETH Zurich</b>   <i>Advisor:</i> Prof. Dr. Melanie Zeilinger <i>Safe Model-Based Reinforcement Learning</i>	Sept. 2019 - Jan. 2020
	<ul style="list-style-type: none"><li>Performed sample efficient learning using Thompson sampling and open-loop Model Predictive Control.</li><li>Augmented model-based Reinforcement Learning with Scenario-based Optimization arguments to obtain safety-certified algorithms.</li></ul>	
	<b>Georgia Institute of Technology</b>   <i>Advisor:</i> Dr. Fumin Zhang <i>GT-MAB: Miniature Autonomous Blimps</i>	May 2015 - April 2016
	<ul style="list-style-type: none"><li>Performed system identification and developed PID controllers to control 3D motion of a robotic helium blimp.</li><li><b>Nano Blimp:</b> developed hardware and software for communication protocol for smaller version of blimp.</li></ul>	
INDUSTRY EXPERIENCE	<b>NNAISENSE, Lugano</b> Research Intern	October 2021 - April 2022
	<ul style="list-style-type: none"><li>Proposed transfer-learning approach to enable fast and efficient adaptation of Recurrent Neural Network models of dynamical systems.</li><li>Designed Lyapunov-based safety certificates for formal verification of model-based Reinforcement Learning algorithms.</li></ul>	
	<b>Georgia Tech Research Institute</b> Co-op Intern: Robotics and Image Processing	Fall 2015, Spring 2016, Summer 2017
	<ul style="list-style-type: none"><li>Implemented and deployed path-planning algorithms in Python (ROS framework) for an agricultural ground robot to autonomously navigate poultry houses.</li><li>Collaborated with poultry scientist to develop novel obstacle (chicken) avoidance routines using computer vision and 3D point cloud data from Xbox Kinect.</li><li>Designed Windows GUIs in C# to run a pedestrian tracking software and identify ideal road-crossing locations for the Georgia Department of Transport.</li></ul>	

JOURNAL PAPER	<b>On the adaptation of recurrent neural networks for system identification.</b> <i>Automatica</i> , Volume 155, ISSN: 0005-1098. doi.org/10.1016/j.automatica.2023.111092. 2023. M. Forgione, <b>A. Muni</b> , D. Piga, M. Gallieri.	
CONFERENCE PAPERS	<b>Designing Biological Sequences via Meta-Reinforcement Learning and Bayesian Optimization.</b> <i>NeurIPS Workshop on Machine Learning in Structural Biology</i> . 2022. L. Feng, P. Nouri, <b>A. Muni</b> , Y. Bengio, P. Bacon.	
	<b>Autopilot Design for a class of Miniature Autonomous Blimps.</b> <i>IEEE Conference on Control Technology and Applications</i> . Pages:841-846. 2017. S. Cho, V. Mishra, Q. Tao, P. Varnell, M. King-Smith, <b>A. Muni</b> , W. Smallwood, F. Zhang.	
	<b>Robotics for Poultry House Management.</b> <i>ASABE Annual International Meeting</i> . 1701103.(doi:10.13031/aim.201701103). 2017. C. T Usher, W. D Daley, B. P Joffe and <b>A. Muni</b> .	
	<b>Control Theory – Autonomous Blimp.</b> <i>IEEE Control Systems Society Video Contest</i> . Available Online: <a href="#">YouTube video</a> . 2015. Q. Tao, M. King-Smith, <b>A.D. Muni</b> , V. Mishra, S. Cho, J.P. Varnell, F. Zhang.	
TALKS	<b>Opening the Black Box: High-dimensional Safe Policy Search via Sim-to-Real.</b> <i>16<sup>th</sup> Workshop for Women in Machine Learning (WiML), NeurIPS 2021</i> . <b>A. Muni</b> , M. Turchetta, A. Krause.	
	<b>Learning-Based Control for Constrained Systems using Thompson Sampling and Scenario Optimization.</b> <i>Machine Learning Summer School (MLSS), Tübingen</i> . 2020. Available: <a href="#">YouTube video</a> . <b>A. Muni</b> , K. Wabersich, M. Zeilinger.	
	<b>3D Reconstruction of Live Chickens in Poultry Houses.</b> <i>13<sup>th</sup> Annual Undergraduate Research Spring Symposium, Georgia Tech</i> . 2018. <b>A. Muni</b> and Colin Usher.	
HONORS AND AWARDS	Women in AI - Excellence Scholarship, Mila	2022-2025
	<a href="#">Navigation Challenge Winner</a> , Montreal Robotics Summer School	2022
	Kyunghyun Cho Diversity Award, Mila	2022
	UdeM/Mila PhD Tuition Exemption for International Students	2022
	NeurIPS Travel Grant, WiML Workshop	2021
	Best Oral Presentation, 3 <sup>rd</sup> position, Undergraduate Research Symposium	Spring 2018
	Best Overall Design Award, <i>MLH MakeHarvard</i> Hackathon	Spring 2018
	3x President's Undergraduate Research Award	2018, 2016, 2015
	ThinkSwiss Research Scholarship	Summer 2017
	James G. and Mary G. Wohlford Co-op Scholarship	Spring 2017
	IEEE Control System Society Video Contest, 3 <sup>rd</sup> position	Summer 2015
TEACHING EXPERIENCE	<b>Teaching Assistant for Differential Equations</b> <i>Georgia Tech School of Mathematics</i>	Jan. 2016 – May 2016
	<b>Peer Tutor for Differential Equation</b> <i>Georgia Tech Center for Academic Success</i>	Sept. 2014 – Sept. 2015
DIVERSITY, EQUITY AND INCLUSION	Co-founder, <a href="#">Women@Mila Meetups</a>	2023
	Organizing team member, Montreal Robotics Summer School	2023, 2022
	Lead mentor and organizing team member, Women in AI & Robotics Hackathon	2022
	Undergraduate Research Ambassador, Georgia Tech	2017 - 2018
	Communications Chair, Women in Electrical & Computer Engineering Club	2015 - 2018

LEADERSHIP AND SERVICE	Reviewer: ICML, Decision Awareness in Reinforcement Learning Workshop	2022
	Panelist: “Designer Farms”, Wharton Agribusiness & Food Security Club, UPenn	2020
	School of Electrical and Computer Engineering Ambassador, Georgia Tech	2014 - 2015
	Volunteer tutor for underprivileged students from K-5 <sup>th</sup> grade in Atlanta	2013 - 2014
SEMINARS AND SUMMER SCHOOLS	Deep Learning and Reinforcement Learning (DLRL) Summer School, Montreal	July 2023
	Montreal Robotics Summer School, Mila	August 2022
	AGI Safety Fundamentals Program, Effective Altruism Cambridge	Spring 2022
	Machine Learning Summer School (MLSS), Tübingen	July 2020
	ETH Robotics Summer School: “ <i>Real World, Real Environments</i> ”	July 2019